

## Jorge Roa

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Motivated robotics and automation engineer with expertise in hardware, software, electronics, and electromechanical systems, passionate about leveraging AI to drive the future of automation and robotics. Experienced in CAD and 3D printing for prototyping and product development. Committed to continuous learning, innovation, and problem-solving. Proficient in working independently or leading teams to deliver cutting-edge technology solutions in fast-paced environments.

Education —	
08/2020 – 08/2022 College Station, USA	M.S.   Engineering Technology Texas A&M University
	Thesis: Design and Implementation of an Automated Asphalt Robotic Testing System
08/2017 – 08/2020 College Station, USA	B.S.   Mechatronics Engineering Texas A&M University
01/2019 – 05/2019	<b>Massachusetts Institute of Technology XPRO</b> An online additive manufacturing course on the fundamentals, applications, and business implications of 3D printing for design and manufacturing.
Publications an	d Awards
	<b>Co-Inventor on US Provisional Patent Application No. 63/421,360</b> Filed November 1, 2022, for "Automated Asphalt Testing Systems and Associated Methods"
09/2021	<ul> <li>Ceramic Binder Jetting Additive Manufacturing: Effects of Powder Particle Size Distribution on Density. Journal of Manufacturing Science and Engineering https://doi.org/10.1115/1.4050306</li> <li>Collaborated with multiple PhD students to research and manufacture multimodal powder feedstock for Binder Jetting Additive Manufacturing.</li> <li>Conducted data collection through various experimental methods and analyzed analytical models to investigate the packing density of ceramic feedstock.</li> <li>Led and managed a team of 8 undergraduate students in designing, developing, and constructing a custom Binder Jetting 3D printer, aimed towards advancing research in biomedical applications of high-density ceramic parts.</li> </ul>
08/2020	<ul> <li>First Place SHELL-ECO Marathon Autonomous Competition https://engineering.tamu.edu/news/2020/09/texas-am-engineering-student-team-wins-shell- eco-marathon-global-competition.html</li> <li>Participated as team leader for the Texas A&amp;M Team. In charge of the PID controls of the simulated car. Software would be subscribed to ROS topics from values generated from path planning, perception, and control algorithms for an autonomous vehicle.</li> <li>Lead testing and optimization of the autonomous vehicle in Microsoft AirSim with Unreal Engine.</li> </ul>
10/2021	<b>First Place Techaton Engineering Competition</b> Placed first in a 36-hour competition by designing and successfully implementing a battery powered device to measure stress levels of a police officer during a traffic stop.



## Work experience

08/2022 - present **Research Scientist Texas A&M Transportation Institute** College Station, TX, USA Invented and patented an advanced automated robotic asphalt testing system, sponsored by TxDOT. Led hardware, software, and electronics development with exceptional results. Developed a complete Linux-based robotic software ecosystem, including a user-friendly • Python3 and PyQt5 UI, IoT communication, multi-threading, and custom C++ machine control code. Implemented multidisciplinary projects on time, from prototype to product. Showcased hands-on design engineering expertise through CAD modeling, mechanical assemblies, complex electronics boards, protoboards, PCBs, and power electrical systems. Graduate Research Assistant Texas A&M University Conducted research on robotics and automation within the transportation sector, leveraging innovative technologies and robotics to transform manual testing processes into efficient, automated solutions. 01/2020 - 06/2021 Graduate teaching assistant College Station, TX, USA Texas A&M University Developed sensor feedback controls, path planning strategies, and maintained 30+ mobile robots while creating teaching materials, instructional videos, and software documentation; taught, supervised, and graded 60+ undergraduate students in five Mobile Robotics Laboratory sections. 01/2020 - 12/2020**Undergraduate Teaching Assistant** College Station, TX, USA Texas A&M University Successfully instructed over 60 undergraduate students per semester in the Mobile Robotics laboratory, utilizing virtual teaching methods. • Devised and implemented an innovative virtual platform for teaching mobile robotics remotely during the COVID-19 pandemic.

Assisted with the development of course materials, grading assignments, and providing feedback to students.

## **Other Experience**

## **Open-Source Mobile Robot Platform Collaborator**

https://www.scuttlerobot.org/team/

- Designed and implemented sensor feedback controls for differential drive robot to optimize path planning. Wrote teaching manuals and produced instructional videos on YouTube for an open-source teaching platform
- Created comprehensive software documentation to facilitate user understanding and ease of use.

06/2021 - 08/2022 College Station, TX, USA